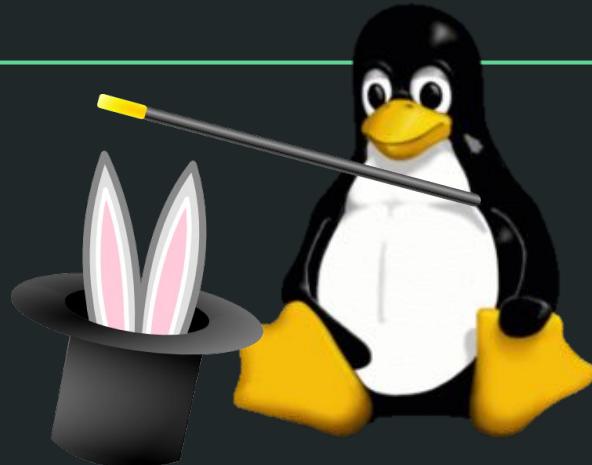


# RCU in 2019

Joel Fernandes <[joel@joelfernandes.org](mailto:joel@joelfernandes.org)>  
Google.



# What I do? Recent work history

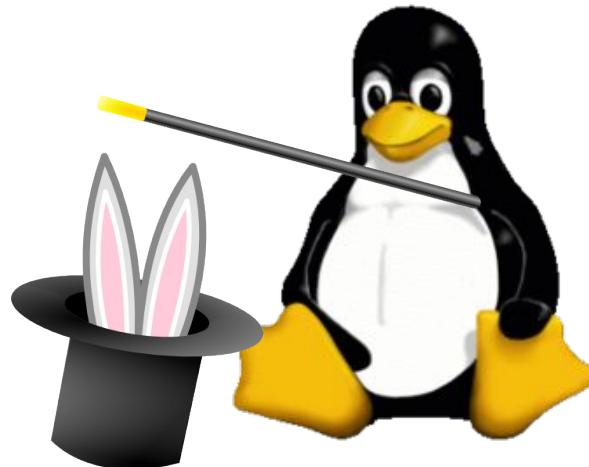
- Joined Google in 2016 : Task Scheduler , BPF for tracing etc.
  - Complex stuff



ANDROID

# What I do? Recent work history

- 2017: Start exploring RCU internals:
  - Very complex stuff



# What I do? Recent work history

- 2019: Parenting a 2 year old
  - Very Very complex stuff



# How I got started with RCU?

- Worked on Linux for a decade or so.
- People who understand RCU internals ... < 7 : Opportunity!!
- Making sense of RCU traces, logs, concepts.

Time to put mysteries to end.

# What am I doing with RCU now?

- Helping community / company with RCU issues, concepts, improvements, reviewing.
- New feature development.

# Who am I ; and how I got started with RCU?

Started questioning RCU's internal design (~2 years ago)

Paul McKenney says... “Here is  
your nice elegant little algorithm”



# Who am I ; and how I got started with RCU?

Paul McKenney says... “Here  
is your nice elegant little  
algorithm equipped to survive  
in the Linux Kernel”



# Credits

RCU is the great decades-long work of Paul Mckenney and others. I am relatively new on the scene (^ 2 years).

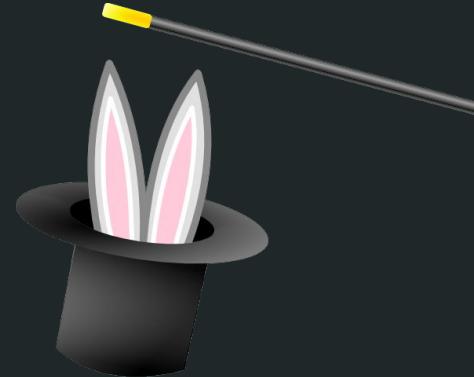
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# Agenda

- Introduction
- TREE RCU
- RCU Flavor consolidation
  - Performance
  - Scheduler Deadlock fixes
- TASKS RCU
- List RCU API improvements (if time permits)

# Introduction

The basic idea of RCU



# Intro: Typical RCU workflow

Say you have some data that you have to share between a reader/writer section.

```
struct shared_data {  
    int a;  
    long b;  
};  
  
int reader(struct shared_data *sd) {  
    if (sd->a)  
        return sd->b;  
    return 0;  
}  
  
int writer(struct shared_data *sd) {  
    sd->b = 1;  
    sd->a = 2;  
}
```

# Intro: Typical RCU workflow

One way is to use a reader-writer lock.

```
int reader(struct shared_data *sd) {      void writer(struct shared_data *sd) {
    read_lock(&sd->rwlock);                  write_lock(&sd->rwlock);
    if (sd->a)                            sd->b = 1;
        ret = sd->b;                      sd->a = 2;
    read_unlock(&sd->rwlock);              write_unlock(&sd->rwlock);
    return ret;                           }
}
```

# Some concepts first: RCU read-side critical section

```
struct shared_data *global_sd;  
  
int reader() {  
    rcu_read_lock();  
    sd = rcu_dereference(global_sd);  
    if (sd->a)  
        ret = sd->b;  
    rcu_read_unlock();  
    return ret; }  
}
```

# Some concepts first: What is a quiescent state?

A state that an entity (CPU or task) passes through that is impossible within an RCU-read side critical section.

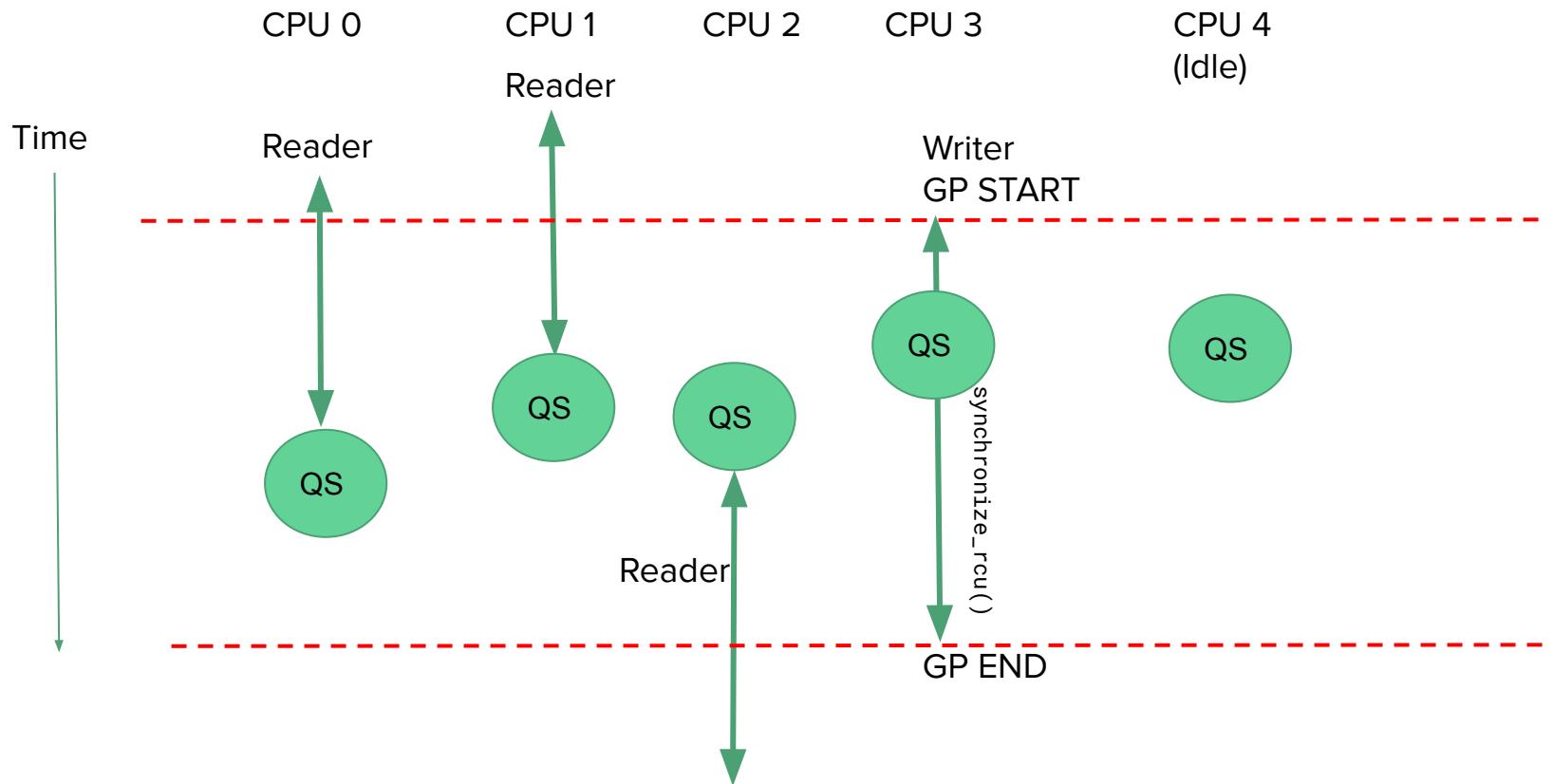
# Some concepts first: What is a Grace period?

A waiting period where we :

- start the wait - by writer
- end the wait - all entities have passed through the Quiescent state.

**Finish GP wait means all readers STARTED PRIOR TO WAIT have finished.**

# Some concepts first: What is a Grace period?



# Intro: Typical RCU workflow

Say you have some data that you have to share between a reader/writer section.

```
struct shared_data {  
    int a;  
    long b;  
};  
  
int reader(struct shared_data *sd) {  
    if (sd->a)  
        return sd->b;  
    return 0;  
}  
  
int writer(struct shared_data *sd) {  
    sd->b = 1;  
    sd->a = 2;  
}
```

# Intro: Typical RCU workflow

One way is to use a reader-writer lock.

```
int reader(struct shared_data *sd) {      void writer(struct shared_data *sd) {
    read_lock(&sd->rwlock);                  write_lock(&sd->rwlock);
    if (sd->a)                            sd->b = 1;
        ret = sd->b;                      sd->a = 2;
    read_unlock(&sd->rwlock);              write_unlock(&sd->rwlock);
    return ret;                           }
}
```

# Intro: Typical RCU workflow: or use RCU...

```
struct shared_data *global_sd;

int reader() {
    rcu_read_lock();
    struct shared_data sd =
        rcu_dereference(global_sd);
    if (sd->a)
        ret = sd->b;
    rcu_read_unlock();
    return ret;
}

void writer() {
    struct shared_data *sd, *old_sd;
    spin_lock(&sd->lock);
    old_sd = rcu_dereference(global_sd);
    sd = kmalloc(sizeof(struct shared_data));
    *sd = *old_sd;
    sd->a = 2;
    rcu_assign_pointer(global_sd, sd);
    spin_unlock(&sd->lock);
    synchronize_rcu();
    kfree(old_sd);
}
```

# Intro: Fastest Read-mostly Primitive

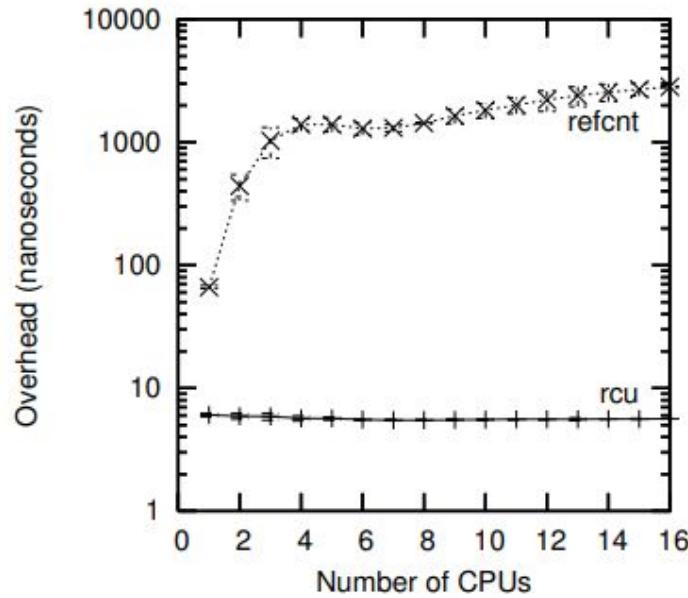


Figure 5: The overhead of entering using RCU as a reference count compared to the overhead of using a shared integer.

# Intro: Writes are costly

What is cost?

- Grace period cycle.
- Time.

But...

- Writes are costly but per-update cost is amortized.
- 1000s or millions of updates can share GP.

# Intro: When to use RCU vs something else?

- If data structure is updated less than 10% of time.
- Need it for other special use cases.
  - Check Documentation/RCU/checklist.txt
- Many more use cases:
  - Wait for completion, locking, refcount implementation etc.
  - Check RCU decades later paper:  
<https://pdos.csail.mit.edu/6.828/2018/readings/rcu-decade-later.pdf>

# Toy #1 based on ClassicRCU (Docs: WhatIsRCU.txt)

Classic RCU (works only on PREEMPT=n kernels):

```
#define rcu_dereference(p) READ_ONCE(p);
#define rcu_assign_pointer(p, v) smp_store_release(&(p), (v));

void rcu_read_lock(void) { }
void rcu_read_unlock(void) { }

void synchronize_rcu(void)
{
    int cpu;
    for_each_possible_cpu(cpu)
        run_on(cpu);
}
```

QUIZ: Why will this not work on a preemptible kernel?

QUIZ: What are the drawbacks of this?

Ok.. Now let's see the bear!

# TREE\_RCU

TREE\_RCU is the most complex and widely used flavor of RCU.

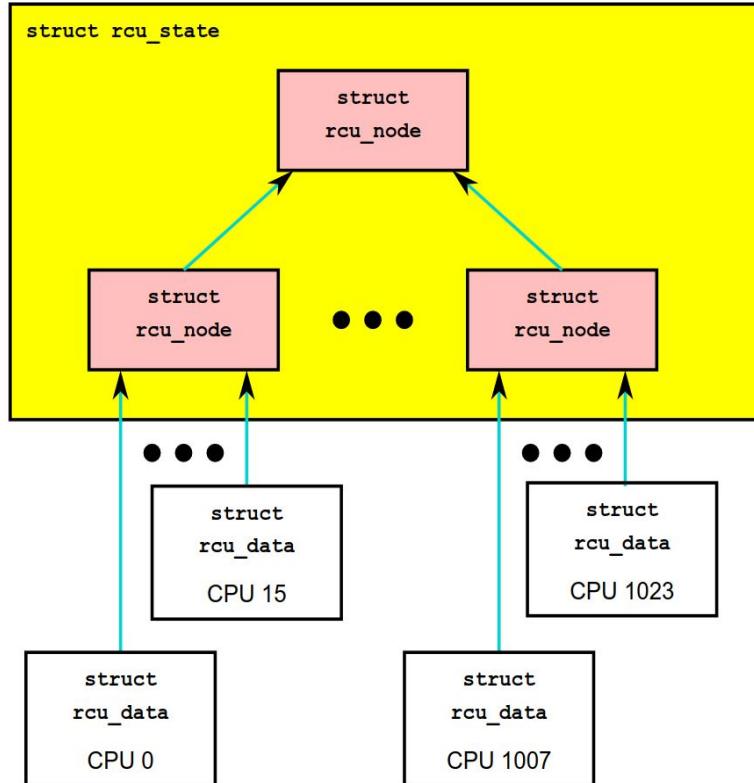
*“If you are claiming that I am worrying unnecessarily, you are probably right. But if I didn't worry unnecessarily, RCU wouldn't work at all! ”*

— Paul McKenney

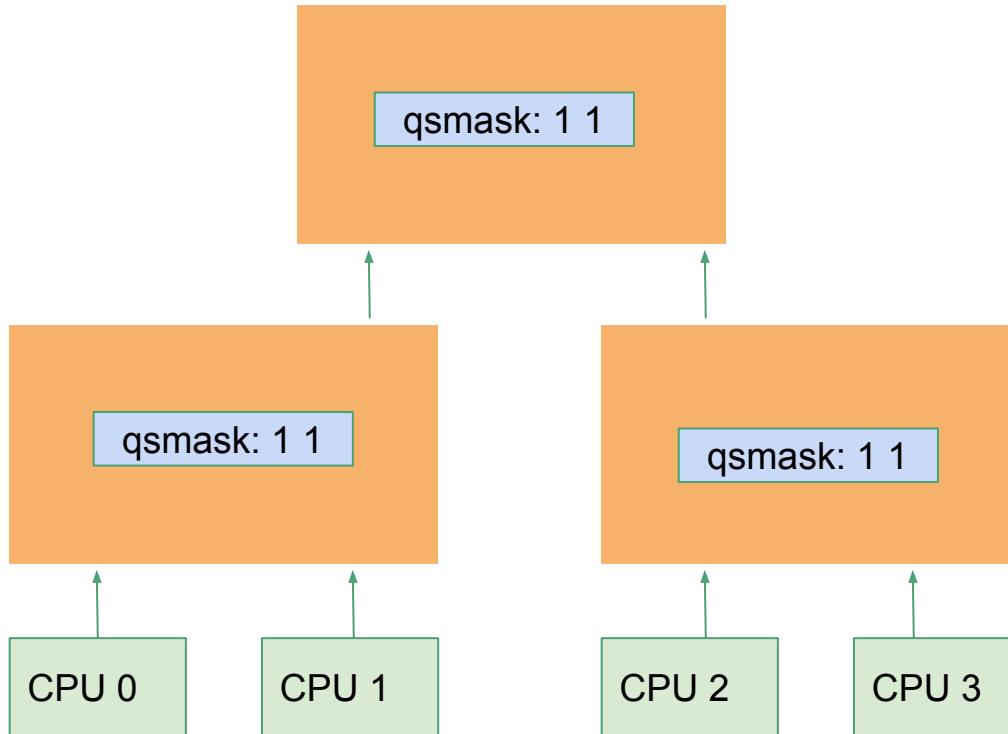
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There's also other specialized flavors: TINY RCU, SRCU, TASKS.

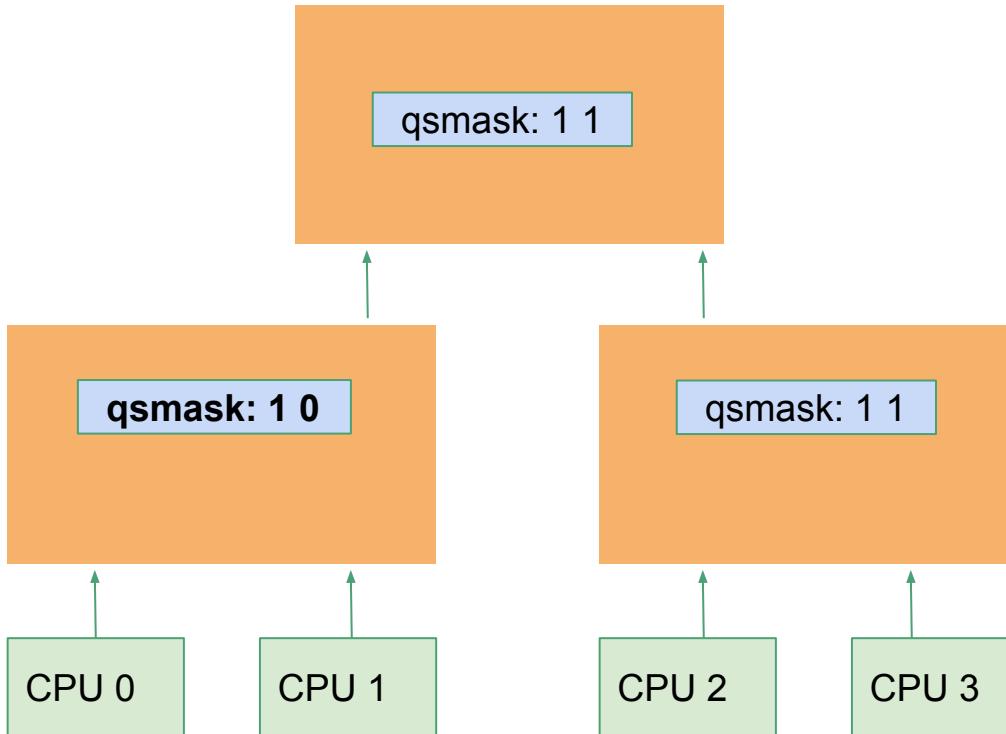
# Intro: How TREE\_RCU works?



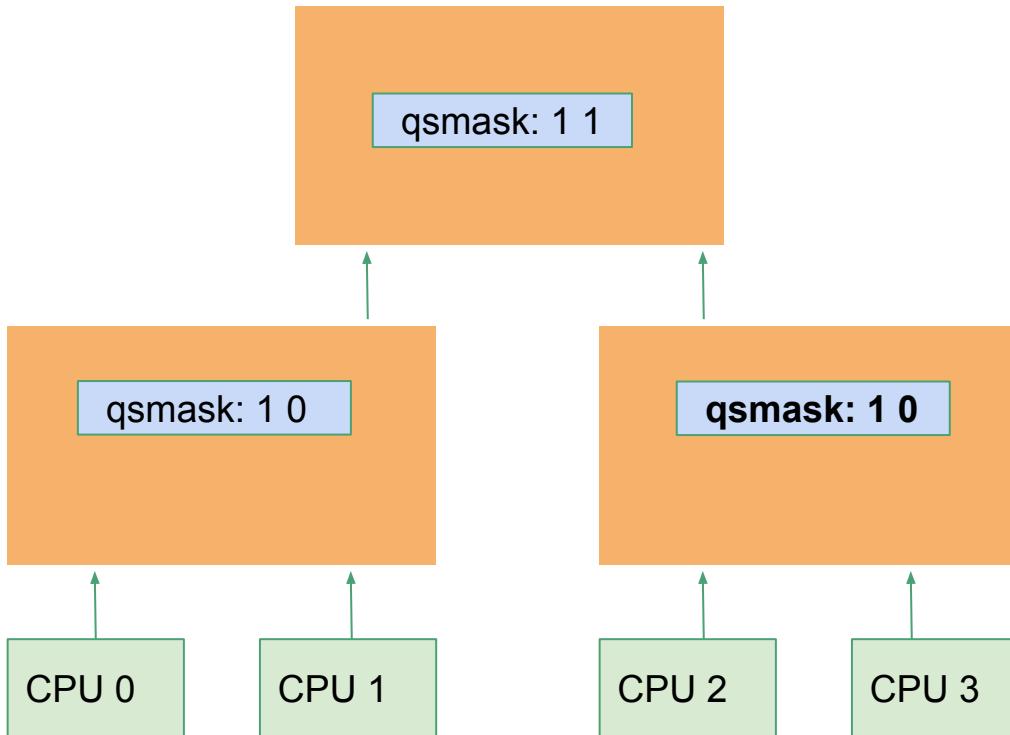
# TREE\_RCU example: Initial State of the tree



# TREE\_RCU example: CPU 1 reports QS

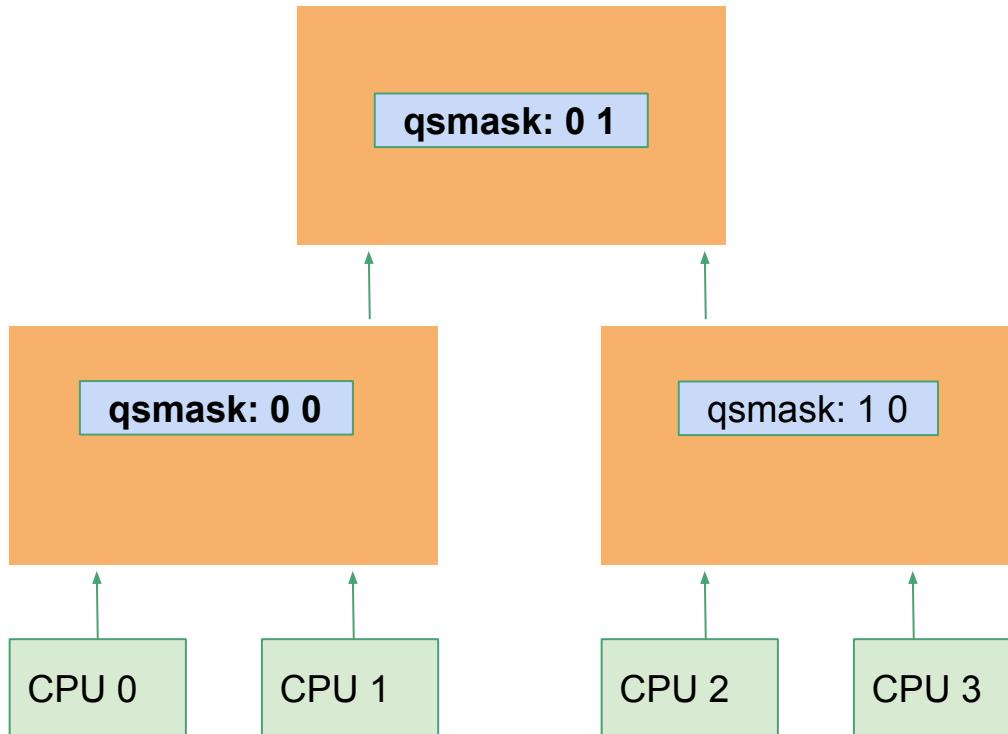


# TREE\_RCU example: CPU 3 reports QS



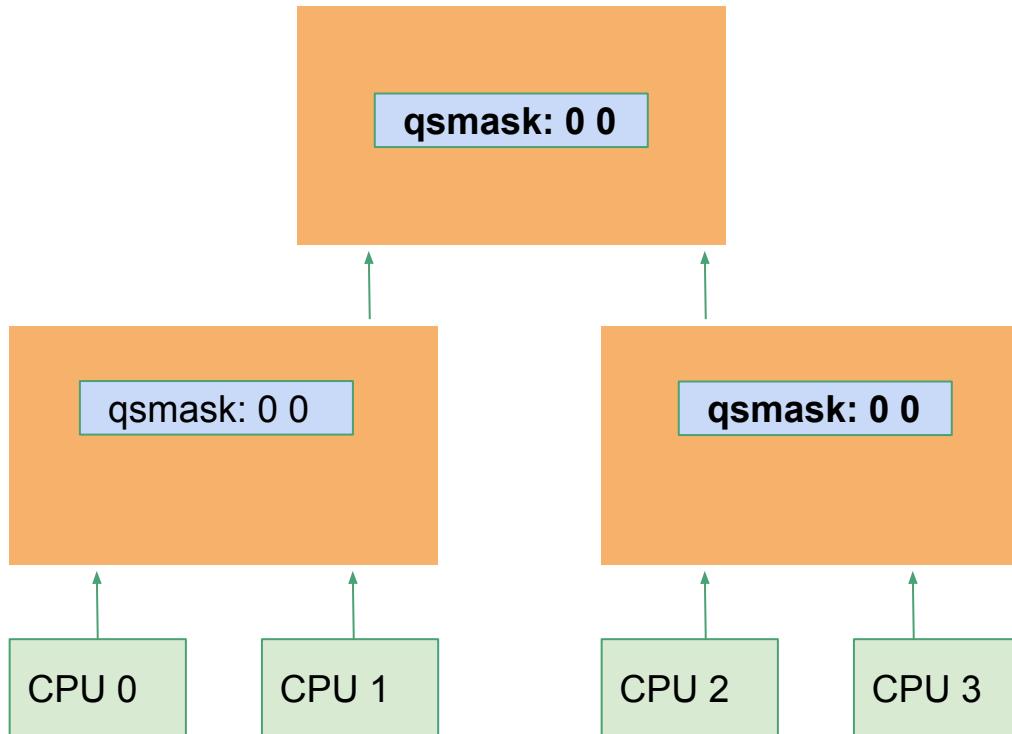
(Notice that the 2 QS updates have proceeded without any synchronization needed)

# TREE\_RCU example: CPU 0 reports QS



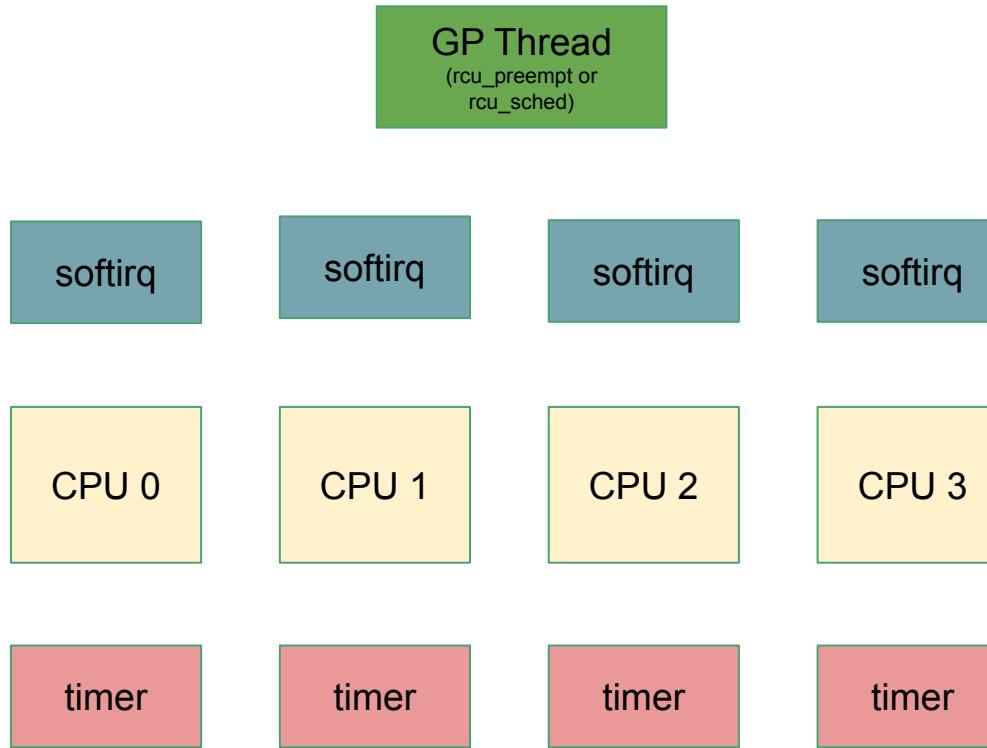
(Now there has been an update at the root node)

# TREE\_RCU example: CPU 2 reports QS

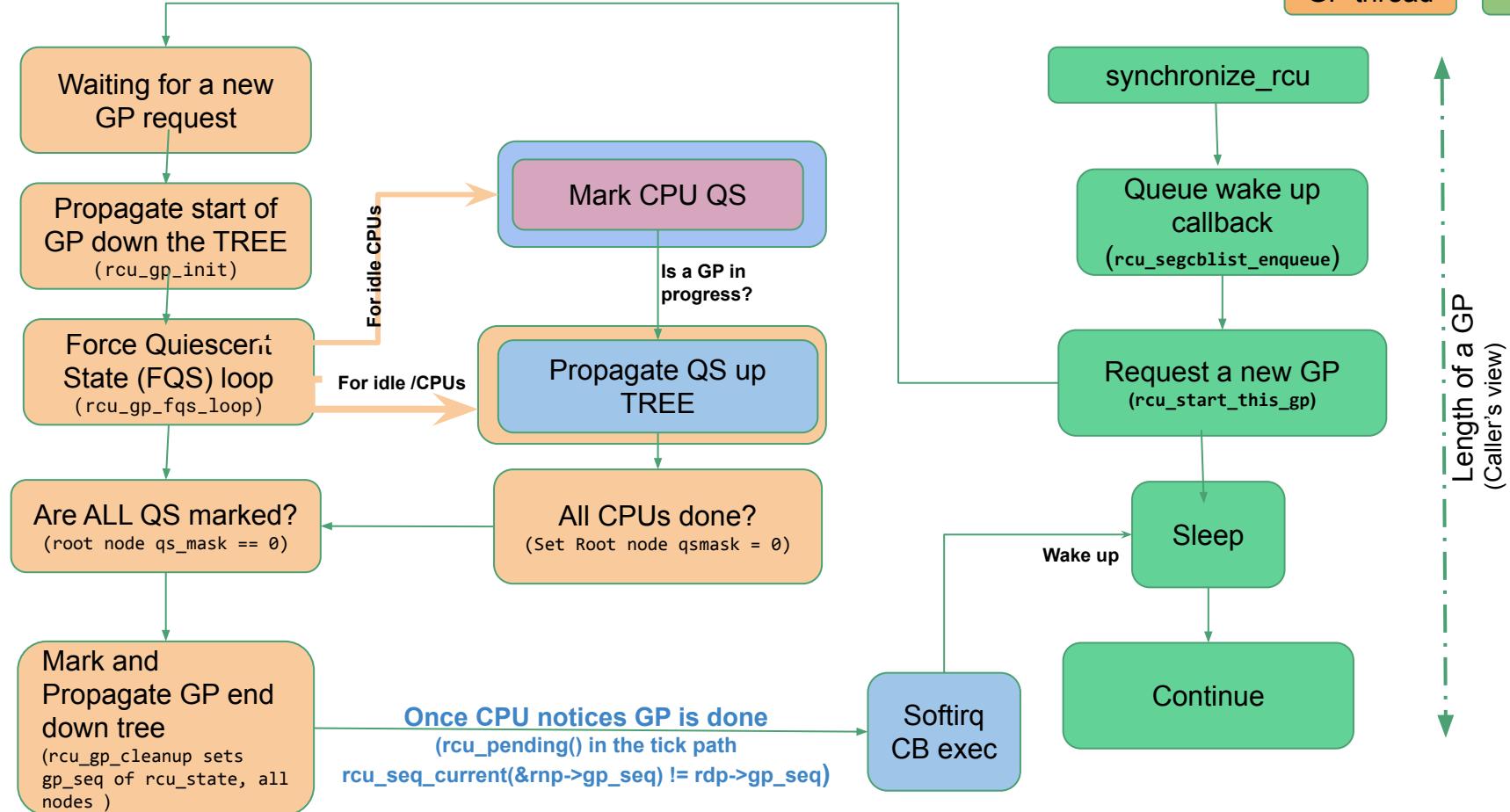
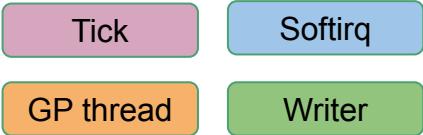


(notice that only 2 global updates were needed instead of 4. On a system with 1000s of CPUs, this will be at most 64)

# Intro: Components of TREE RCU (normal grace period)



# Intro: Life Cycle of a grace period



# Implied QS

- CPU is already in a certain state:
  - IDLE
  - OFFLINE
  - USER MODE

# Light weight QS

- Does not end the grace period yet.
- Just marks CPU-**locally** and someone ELSE reports up the tree LATER.

What happens?

- Start of GP sets **rcu\_data::cpu\_no\_qs**
- Lightweight QS reporting clears it which says CPU is DONE.

Where does it happen?

- Scheduler tick
- Context switch

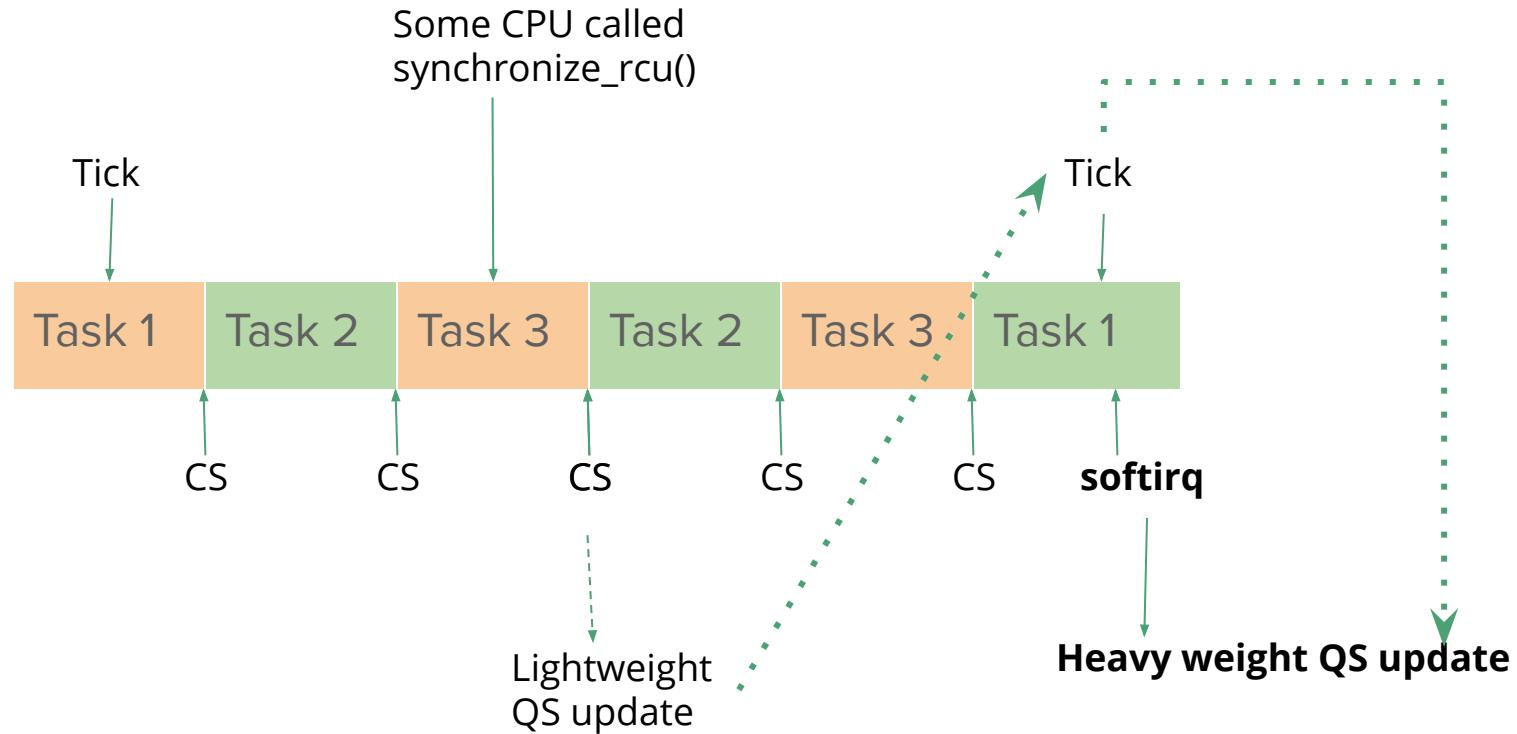
# Heavy weight QS

- Can end the grace period due to tree report.
- Happens less often : Uses mem barriers, atomics, locking etc.
- Happens only AFTER the light weight QS.

Where does it happen?

- softirq
- fqs\_loop
  - Due to transition to NOHZ - idle/user mode
  - cond\_resched() in PREEMPT=n kernels
- rcu\_read\_unlock\_special() in some cases.

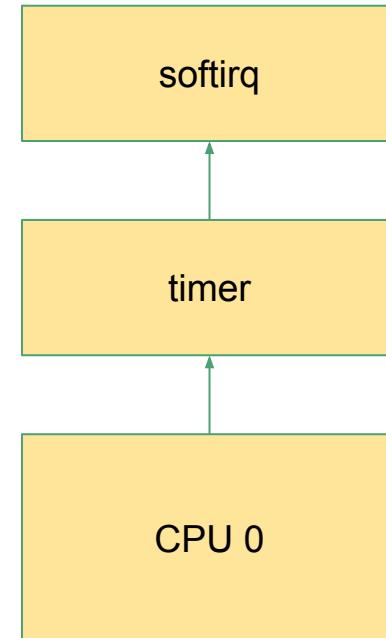
# Example of light weight and heavy weight QS



# Intro: What happens in softirq ?

## Per-CPU Work:

- QS reporting for CPU and propagate up tree.
- Invoke any callbacks whose GP has completed.
  - (TODO: Check that if there are no callbacks queued on CPU, can we skip softirq?)

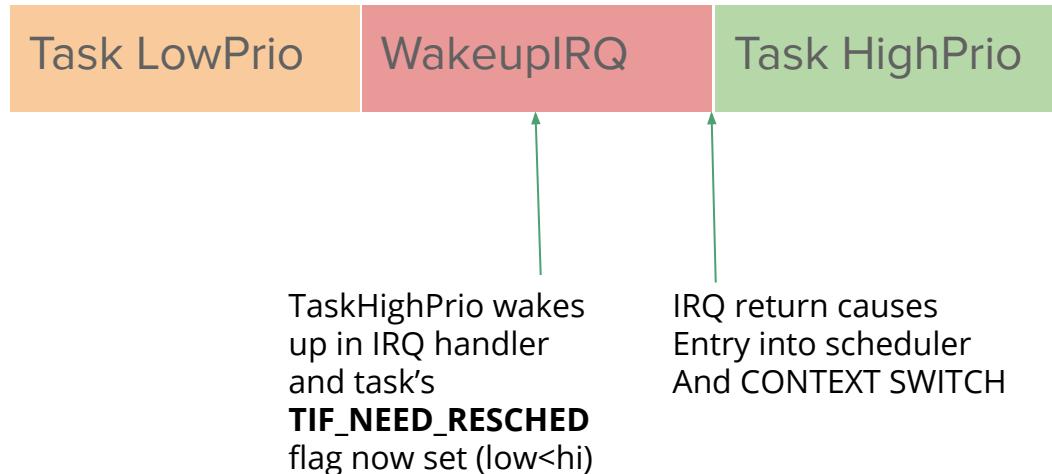


Caveat about callbacks queued on offline CPUs:

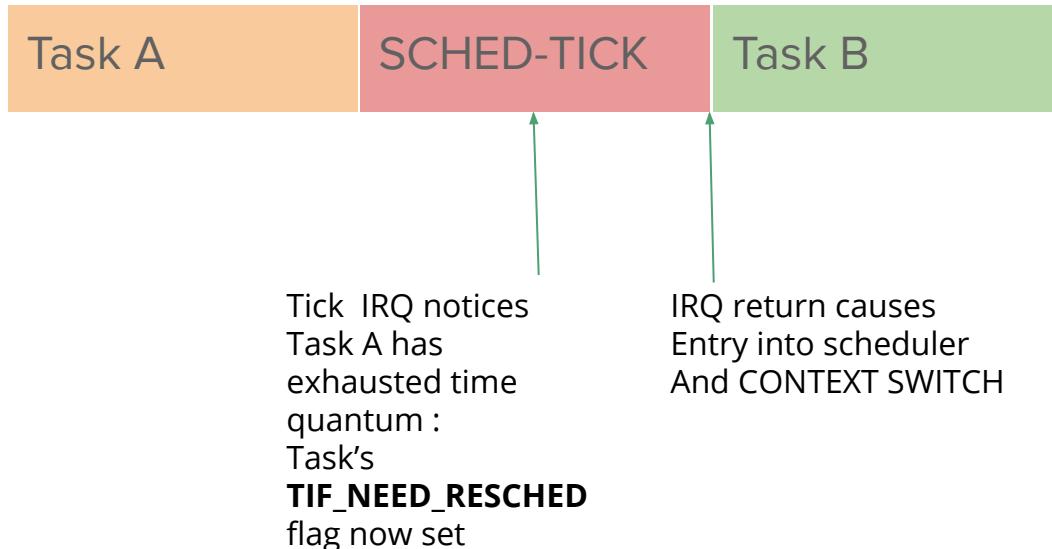
PaulMck says:

> And yes, callbacks do migrate away from non-offloaded CPUs that go  
> offline. But that is not the common case outside of things like  
> rcutorture.

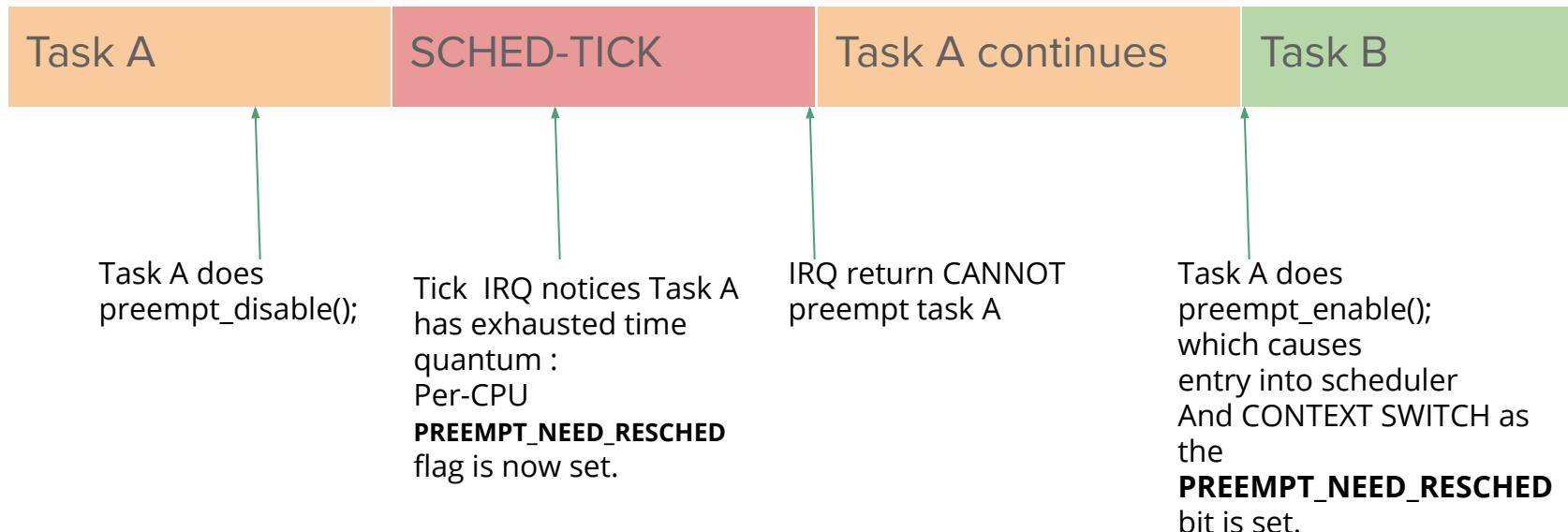
# The magic of {TIF,PREEMPT}\_NEED\_RESCHED



# The magic of {TIF,PREEMPT}\_NEED\_RESCHED

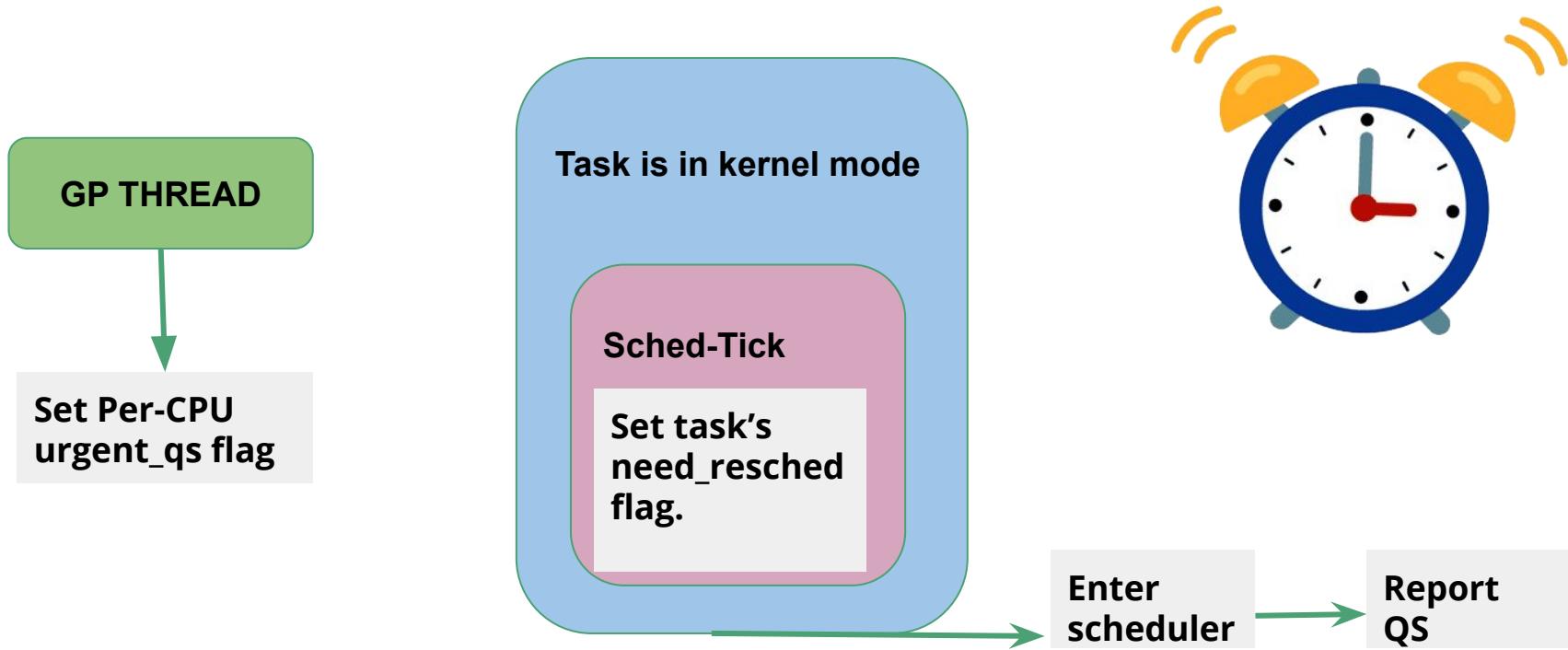


# The magic of {TIF,PREEMPT}\_NEED\_RESCHED



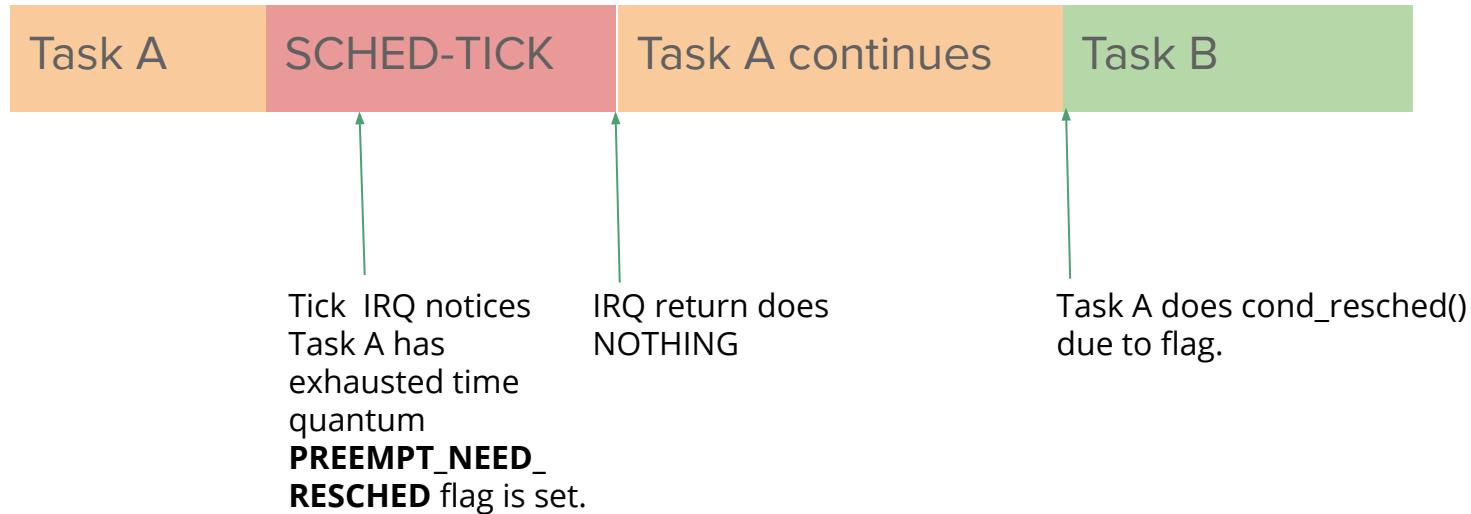
# Intro: Grace Period has started, what's RCU upto?

At around 100ms:



( Note: Scheduler entry can happen either in next TICK or next preempt\_enable() )

# `!CONFIG_PREEMPT` kernels and `cond_resched()`:



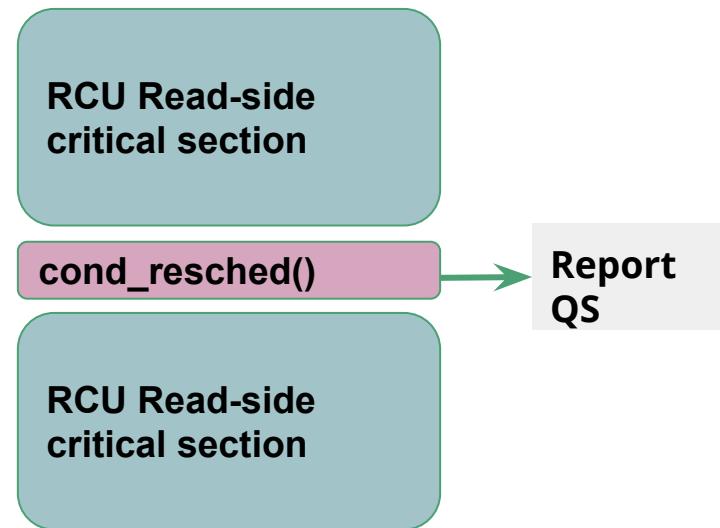
RULE:

cond\_resched() cannot be in rcu reader section.

BAD:

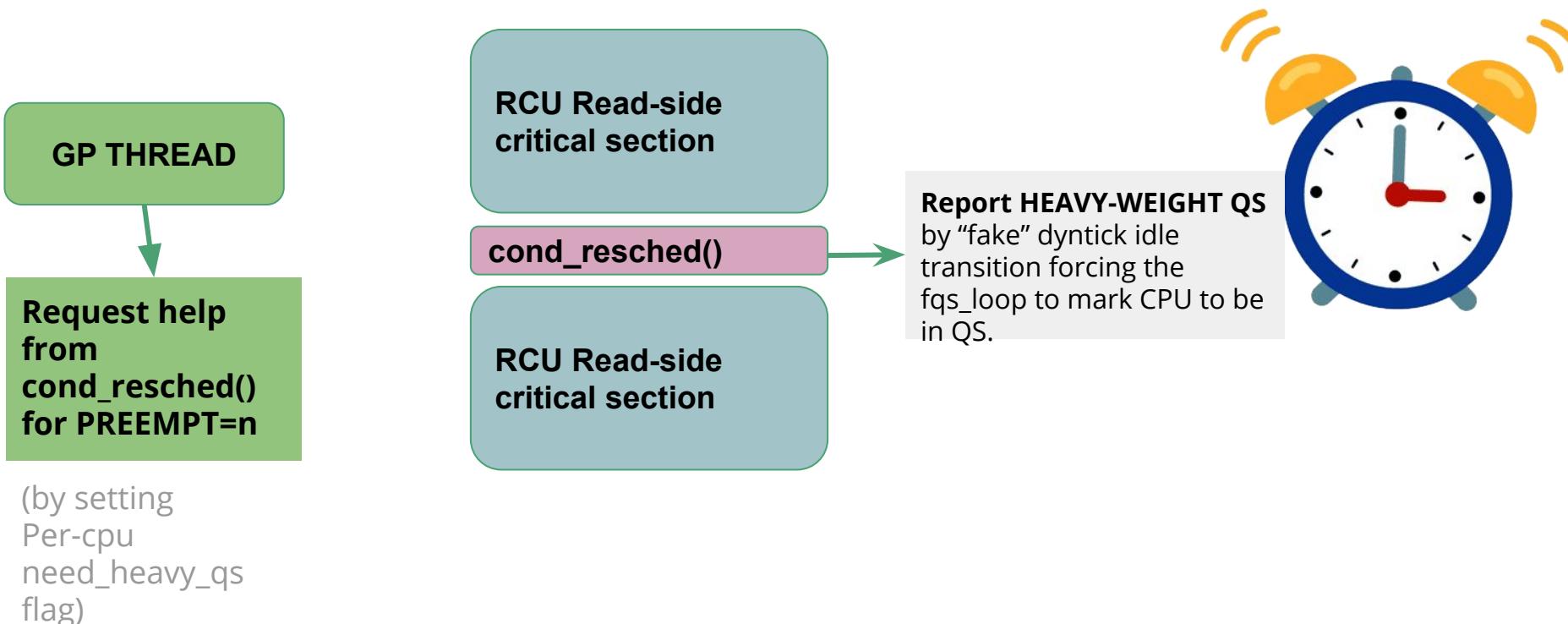
```
rcu_read_lock();  
cond_resched();  
rcu_read_unlock();
```

We can use that to our advantage:



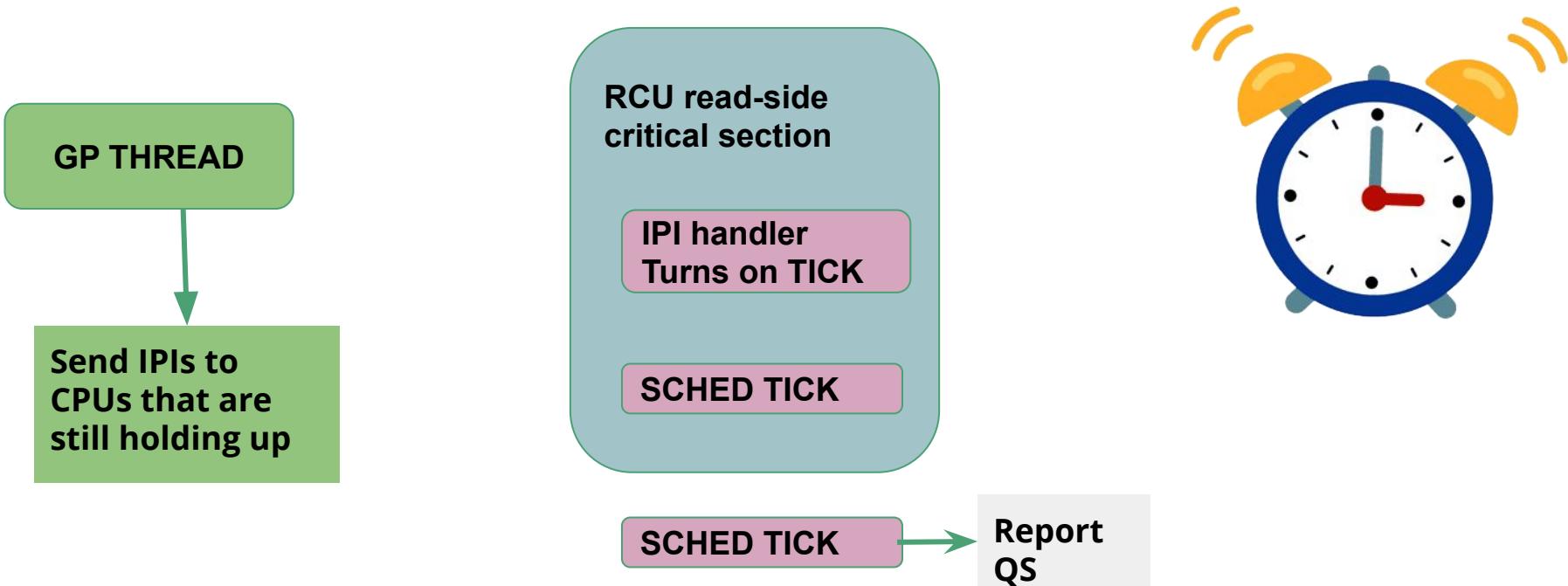
# Intro: Grace Period has started, what's RCU upto?

At around 200ms: Put `cond_resched()` on steroids:



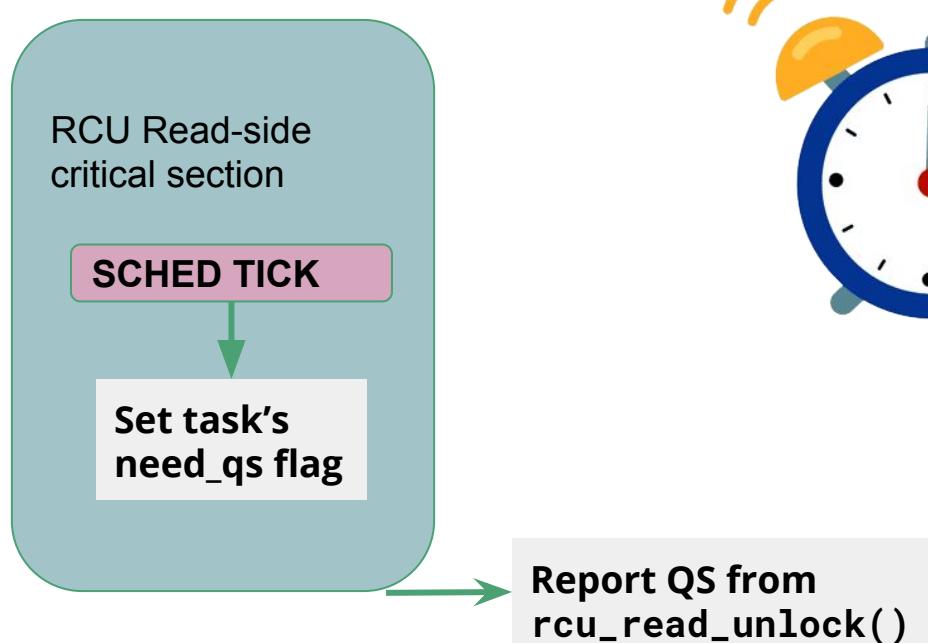
# Intro: Grace Period has started, what's RCU upto?

At around 300ms turn on TICK for nohz\_full kernel mode:



# Intro: Grace Period has started, what's RCU upto?

At around 1 second of start of GP:



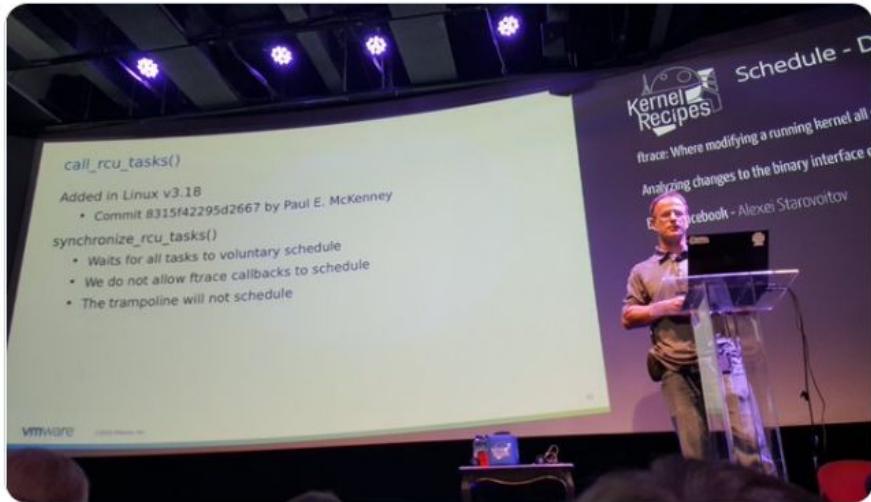
# Tasks-RCU

“We all jump on a ~~yellow submarine~~ dynamic trampoline” -- Beatles



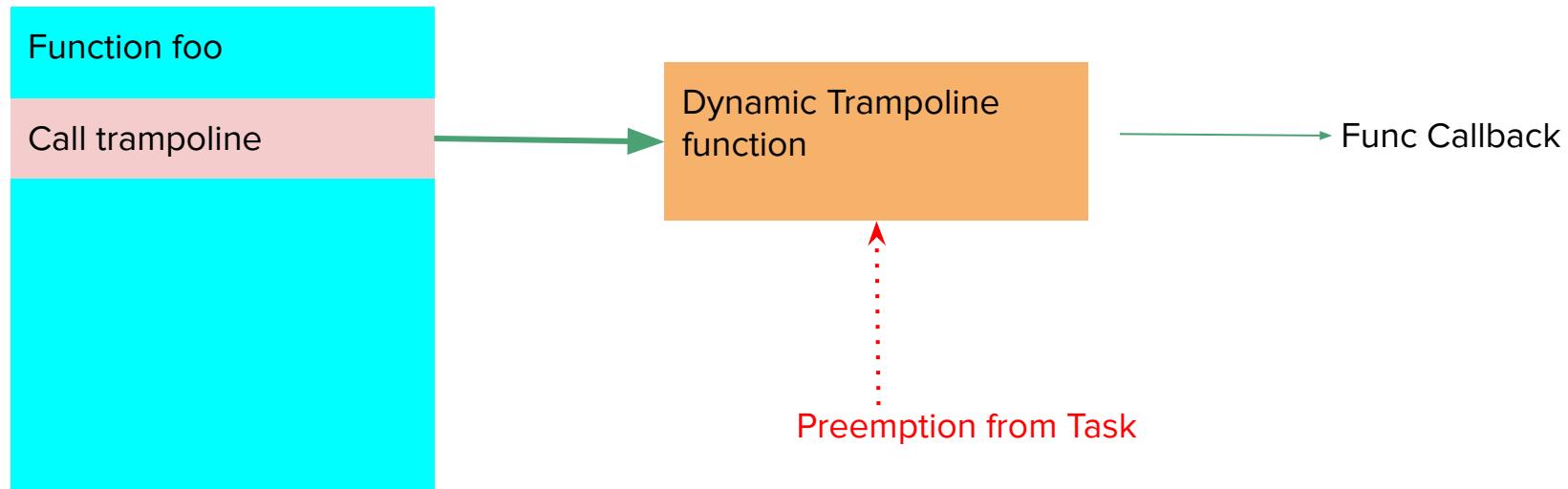
**Adrien** @saruspete · 20h

#kr2019 the 3rd rule of the kernel (after do not break userspace, and BPF is the answer) is "RCU is your sync solution". Just wait for @joel\_linux to explain them :) @srostedt



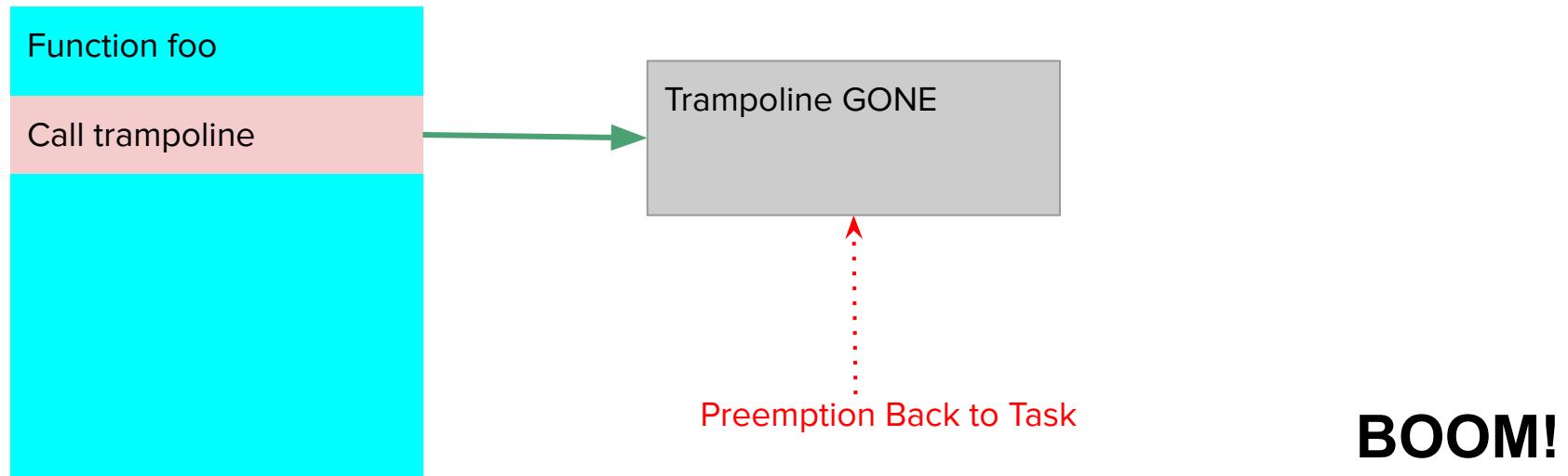
# TasksRCU : For dynamic trampolines

Problem: Ftrace allocates dynamic trampolines for callbacks.



# TasksRCU : For dynamic trampolines

Problem: Ftrace allocates dynamic trampolines for callbacks.



# Solution: TasksRCU

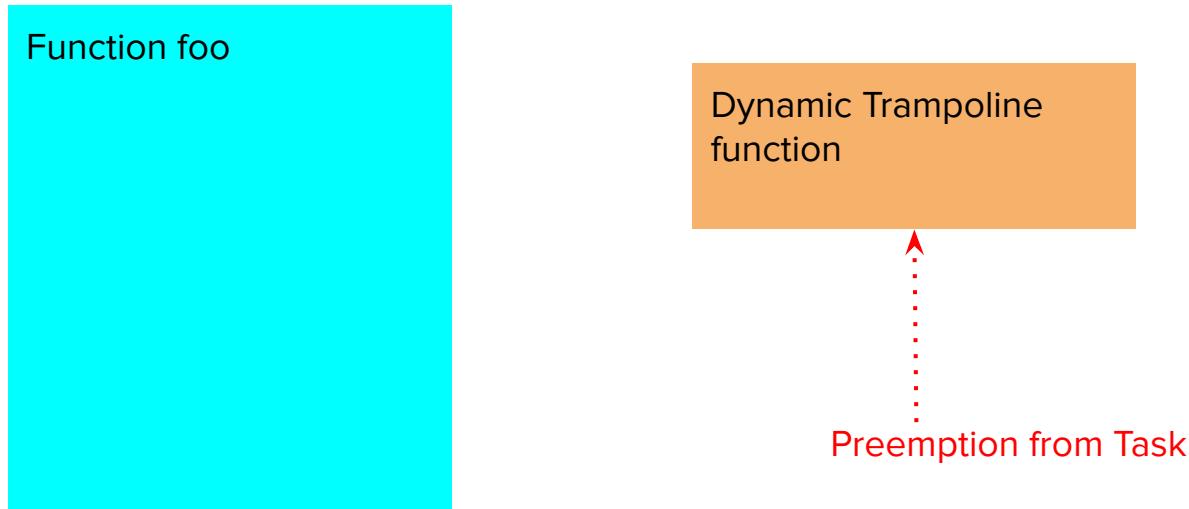
Read-side critical section: Trampoline

Quiescent state: Task blocking

Grace Period: Wait for all tasks to block

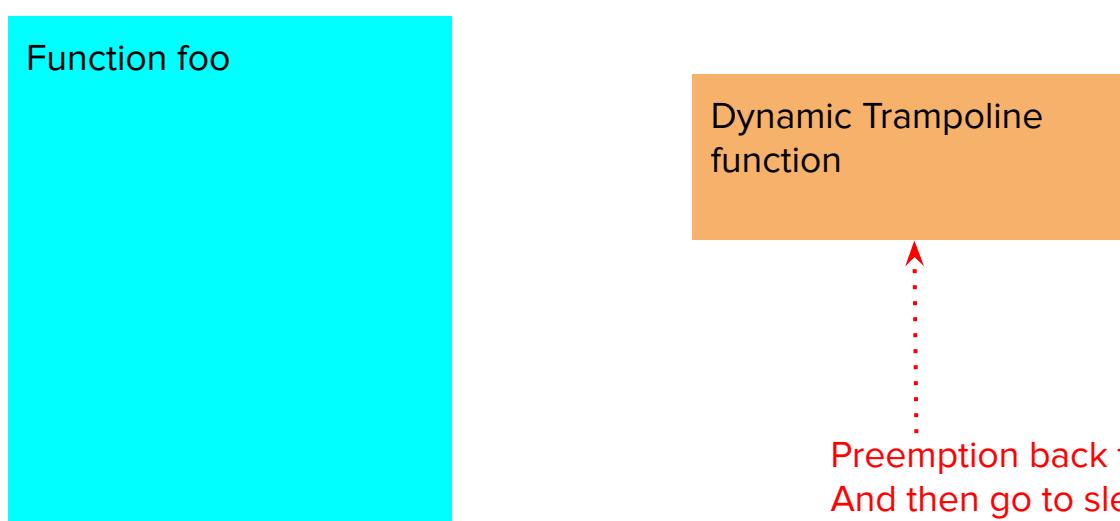
# TasksRCU : For dynamic trampolines

Solution: Disconnect trampoline, but don't free it yet.



# TasksRCU : For dynamic trampolines

Solution: Wait for all tasks to block (`synchronize_rcu_tasks()`).



# TasksRCU : For dynamic trampolines

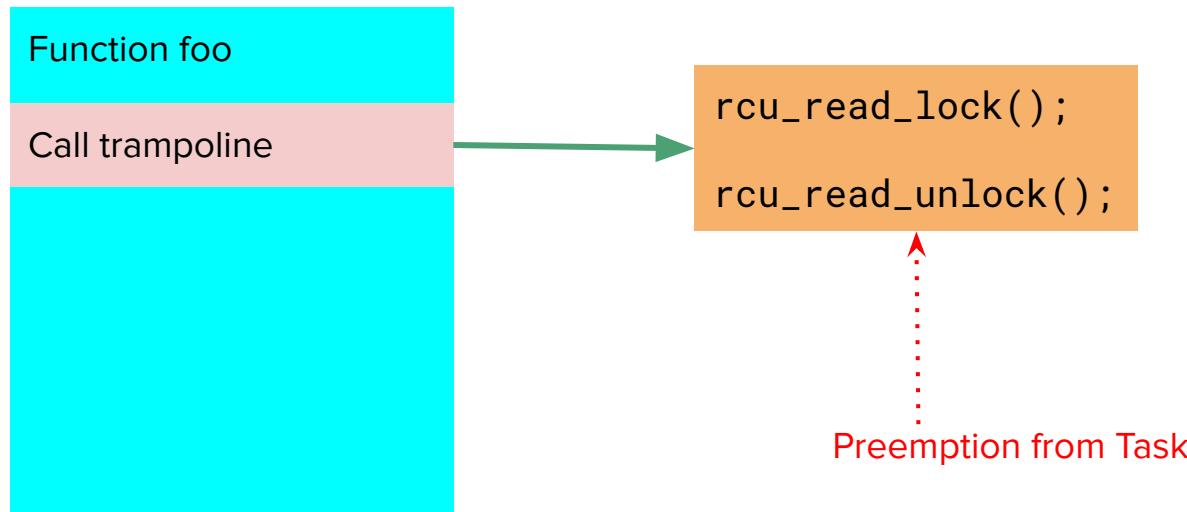
Solution: Free trampoline

Function foo

Trampoline GONE

# TasksRCU : For dynamic trampolines

Why wouldn't `rcu_read_lock()` with `synchronize_rcu()` work?



# RCU Flavor consolidation

---

# Different RCU “flavors”

## **RCU-sched**

**Reader Section: !preemptible();**

Entry into RCU read-side critical section:

- a. rCU\_read\_lock\_sched();
- b. preempt\_disable();
- c. local\_irq\_disable();
- d. IRQ entry.

# Different RCU “flavors”

## **RCU-bh**

### **Reader Section: Bottom half disable**

Entry into RCU read-side critical section:

- a. `rcu_read_lock_bh();`
- b. `local_bh_disable();`
- c. SoftIRQ entry.

# Different RCU “flavors”

## **RCU-preempt**

Reader section:

Marked by `rcu_read_lock()` and `rcu_read_unlock()` pair.

Preemption allowed in reader , blocking not allowed (unless RT patchset).

# RCU Flavor Consolidation: Why? Reduce APIs

## Problem:

1. Too many APIs for synchronization. Confusion over which one to use!
  - a. For preempt flavor: `call_rcu()` and `synchronize_rcu()`.
  - b. For sched: `call_rcu_sched()` and `synchronize_rcu_sched()`.
  - c. For bh flavor: `call_rcu_bh()` and `synchronize_rcu_bh()`.
2. Duplication of RCU state machine for each flavor ...
3. Too many GP threads.

**Now after flavor consolidation:** Just `call_rcu()` and `synchronize_rcu()`.

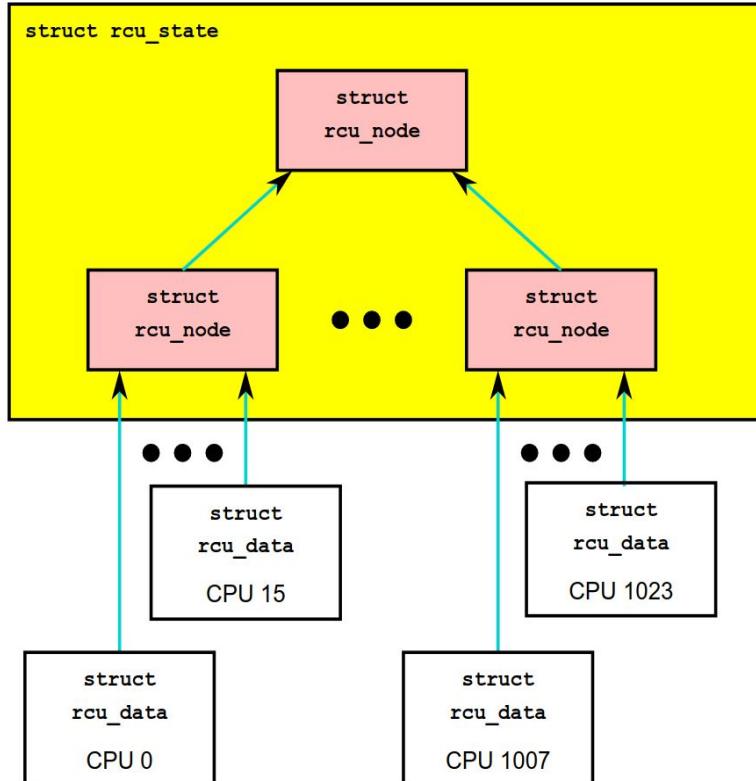
# RCU Flavor Consolidation: Why? Changes to rcu\_state

Why?

- 3 → 1 rCU\_state structures.
- 3 → 1 GP thread and state machines.

Advantages:

- Less resources!
- Less code!



Remember : an RCU reader taking a long time can delay a grace period

CPU 0

```
/* This is start of an RCU reader! */  
rcu_read_lock();  
  
/* This is end of an RCU reader! */  
rcu_read_unlock();
```

CPU 1

```
/* Called after CPU 0's preempt_disable() */  
synchronize_rcu();  
  
/* Executes only much later! */  
some_func();
```

Before consolidation: Grace periods were separated, for example...

CPU 0

```
/* This is start of an RCU reader! */
preempt_disable();
```

```
/* This is end of an RCU reader! */
preempt_enable();
```

CPU 1

```
/* Called after CPU 0's preempt_disable() */
synchronize_rcu();
```

```
/* Can exec before CPU 0 preempt_enable() */
some_func();
```

## After consolidation: synchronize\_rcu() has to wait

CPU 0

```
/* This is start of an RCU reader! */  
preempt_disable();  
  
/* This is end of an RCU reader! */  
preempt_enable();
```

CPU 1

```
/* Called after CPU 0's preempt_disable() */  
synchronize_rcu();  
  
/* Executes only much later! */  
some_func();
```

# rcuperf can prove it.

## What does the rcuperf test do?

- Starts N readers and N writers on N CPUs
- Readers just do `rcu_read_lock()` + `rcu_read_unlock()` in a loop.
- Writers call and measure wall-clock time of `synchronize_rcu()` repeatedly.

## What I did (HACK) : Modified test to busy loop for N ms on reserved CPU:

```
void reserved_thread() {  
    preempt_disable();  
    busy_loop_ms(N);  
    preempt_enable();  
}
```

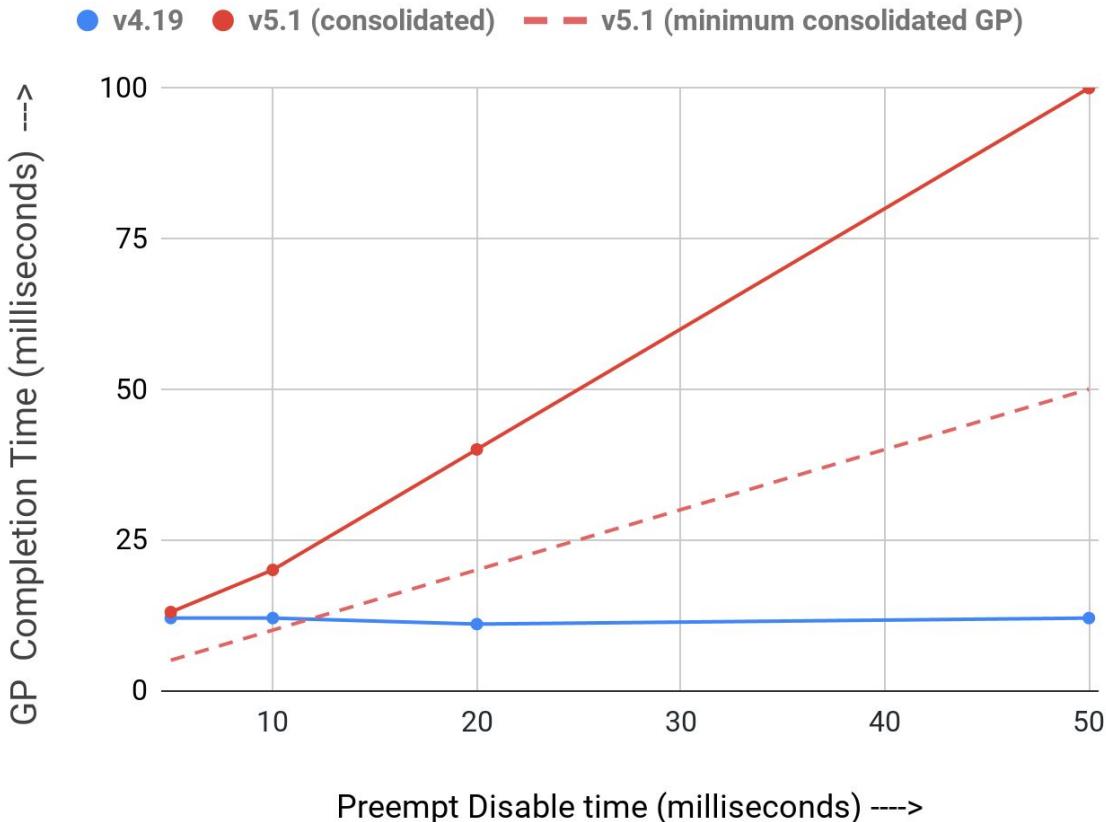
## What could be the expected Results?

# RCU Flavor Consolidation Performance Changes

This is still **within RCU specification!**

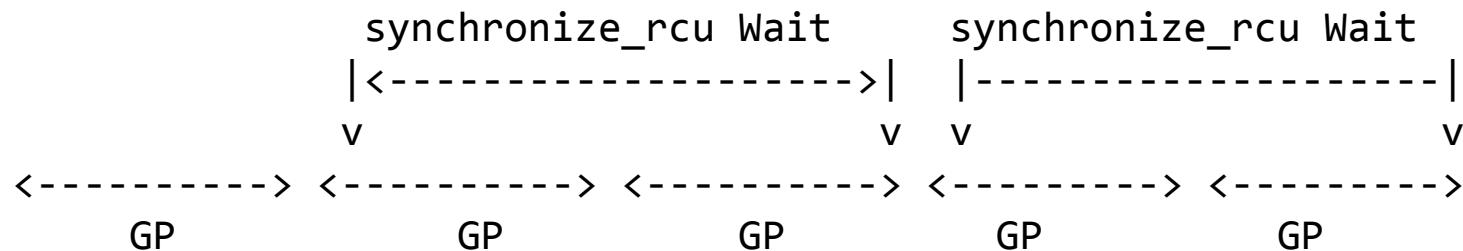
Also note that disabling preemption for so long is most not acceptable by most people anyway.

Comparison of v4.19 and v5.1 with rcuperf mods



# RCU Flavor Consolidation

Notice that `synchronize_rcu` time was 2x the `preempt_disable` time, that's cos:



GP = long preempt disable duration

# Consolidated RCU - The different cases to handle

Say RCU requested special help from the reader section unlock that is holding up a GP for too long....

```
preempt_disable();
rcu_read_lock();
do_some_long_activity(); // TICK sets per-task ->need_qs bit
rcu_read_unlock();      // ... so need help from rcu_read_unlock();
preempt_enable();
```

## RCU-preempt reader nested in RCU-sched due to preempt\_disable()

### Before:

```
preempt_disable();
rcu_read_lock();
do_some_long_activity();
rcu_read_unlock();      // Report QS ASAP
preempt_enable();
```

### Now:

```
preempt_disable();
rcu_read_lock();
do_some_long_activity();
rcu_read_unlock();
    -> rcu_read_unlock_special(); // Defer the QS and set
                                    // bit & set PREEMPT_NEED_RESCHED
preempt_enable(); // Report the QS
```

## Consolidated RCU - The different cases to handle

## RCU-preempt reader nested in RCU-sched due to local\_irq\_disable()

(This is a special case where previous reader requested deferred special processing by setting ->deferred\_qs bit)

**Before:**

```
local_irq_disable();
rcu_read_lock();
rcu_read_unlock()
    -> rcu_read_unlock_special(); // Report the QS
local_irq_enable();
```

**Now:**

```
local_irq_disable();
rcu_read_lock();
rcu_read_unlock()
    -> rcu_read_unlock_special(); // Defer the QS and set
                                    // bit & set PREEMPT_NEED_RESCHED
local_irq_enable(); // CANNOT Report the QS, still deferred.
```

## Consolidated RCU - The different cases to handle

## RCU-preempt reader nested in RCU-sched due to IRQ entry:

(This is a special case where previous reader requested deferred special processing by setting ->deferred\_qs bit)

### Before:

```
/* hardirq entry */  
rcu_read_lock();  
rcu_read_unlock()  
    -> rcu_read_unlock_special(); // Report the QS  
/* hardirq exit */
```

### Now:

```
/* hardirq entry */  
rcu_read_lock();  
do_some_long_activity();  
rcu_read_unlock()  
    -> rcu_read_unlock_special(); // Defer the QS and set  
                                // rcu_read_unlock_special.deferred_qs  
                                // bit & set TIF_NEED_RESCHED  
/* hardirq exit */      // Report the QS
```

## Consolidated RCU - The different cases to handle

## RCU-preempt reader nested in RCU-bh

# Consolidated RCU - The different cases to handle

### Before:

```
local_bh_disable(); /* or softirq entry */  
rcu_read_lock();  
do_some_long_activity();  
rcu_read_unlock(); // Report QS ASAP  
local_bh_enable(); /* or softirq exit */
```

### Now:

```
local_bh_disable(); /* or softirq entry */  
rcu_read_lock();  
do_some_long_activity();  
rcu_read_unlock();  
    -> rcu_read_unlock_special(); // Defer the QS and set  
                                // bit & set PREEMPT_NEED_RESCHED  
local_bh_enable(); /* or softirq exit */ // Report the QS
```

## RCU-bh reader nested in RCU-preempt or RCU-sched

### Before:

```
preempt_disable();  
/* Interrupt arrives */  
/* Raises softirq */  
/* Interrupt exits */  
_do_softirq();  
    -> rcu_bh_qs();          /* Reports a BH QS */  
preempt_enable();
```

### Now:

```
preempt_disable();  
/* Interrupt arrives */  
/* Raises softirq */  
/* Interrupt exits */  
_do_softirq();          /* Do nothing -- preemption still disabled */  
preempt_enable();
```

## Consolidated RCU - The different cases to handle

# Consolidated RCU - The different cases to handle

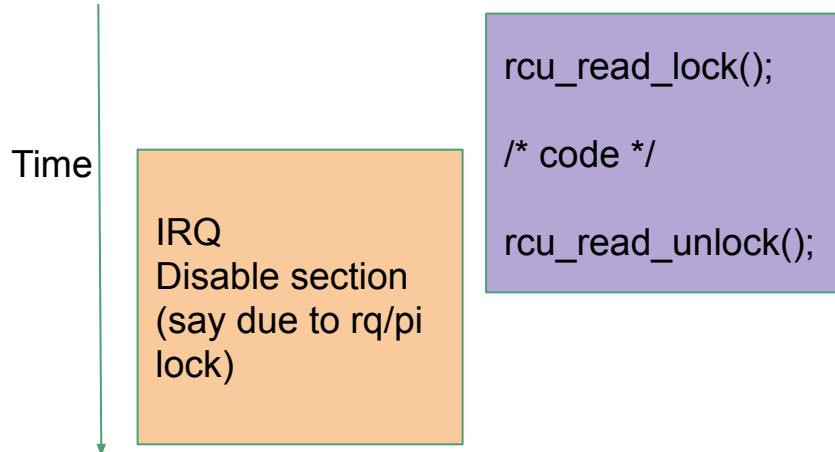
**Solution:** In case of denial of attack, ksoftirqd's loop will report QS.  
No reader sections expected there:

See commit: d28139c4e967 ("rcu: Apply RCU-bh QSes to RCU-sched and  
RCU-preempt when safe")

# Consolidated RCU - Fixing scheduler deadlocks...

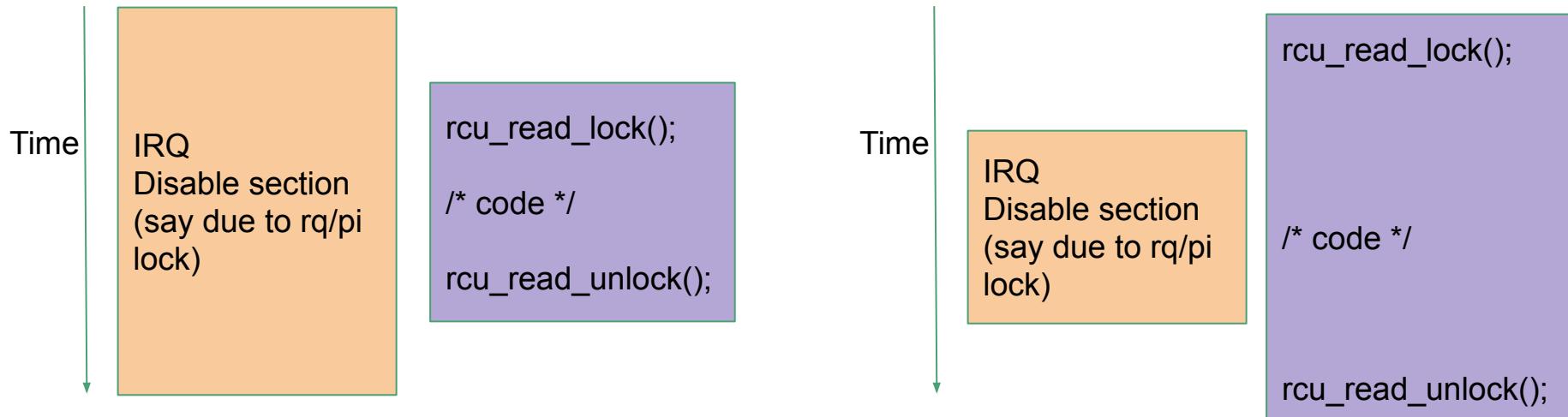
The forbidden scheduler rule... This is NOT allowed (<https://lwn.net/Articles/453002/>)

“Thou shall not hold RQ/PI locks across rcu\_read\_unlock() if thou not holding it or disabling IRQ across both rcu\_read\_lock() + rcu\_read\_unlock()”



# Consolidated RCU - Fixing scheduler deadlocks...

The forbidden scheduler rule... This is ALLOWED:



# Consolidated RCU - Fixing scheduler deadlocks...

But we have a new problem... Consider case: future `rcu_read_unlock_special()` might be called due to a previous one being deferred.

```
previous_reader()
{
    rcu_read_lock();
    do_something();      /* Preemption happened here (so need help from rcu_read_unlock_special. */
    local_irq_disable(); /* Cannot be the scheduler as we discussed! */
    do_something_else();
    rcu_read_unlock();  // As IRQs are off, defer QS report but set deferred_qs bit in rcu_read_unlock_special
    do_some_other_thing();
    local_irq_enable();
}

current_reader() /* QS from previous_reader() is still deferred. */
{
    local_irq_disable(); /* Might be the scheduler. */
    do_whatever();
    rcu_read_lock();
    do_whatever_else();
    rcu_read_unlock(); /* Must still defer reporting QS once again but safely! */
    do_whatever_comes_to_mind();
    local_irq_enable();
}
```

# Consolidated RCU - Fixing scheduler deadlocks...

Fixed in commit: 23634eb (“rcu: Check for wakeup-safe conditions in rcu\_read\_unlock\_special()”)

Solution: Intro rcu\_read\_unlock\_special.b.deferred\_qs bit. (Which is set in previous\_reader() in previous example).

Raise softirq from \_special() only when either of following are true:

- in\_irq() (later changed to in\_interrupt) - because ksoftirqd wake-up impossible.
- deferred\_qs is set which happens in previous\_reader() in previous example.

This makes the softirq raising not wake ksoftirqd thus avoiding a scheduler deadlock.

Made detailed notes on scheduler deadlocks:

[https://people.kernel.org/joelfernandes/making-sense-of-scheduler-deadlocks-in rcu](https://people.kernel.org/joelfernandes/making-sense-of-scheduler-deadlocks-in	rcu)

<https://lwn.net/Articles/453002/>

# Future work

- More Torture testing on arm64 hardware
- Re-design dynticks counters to keep simple
- List RCU checking updates
- RCU scheduler deadlock checking
- Reducing grace periods due to kfree\_rcu().
- Make possible to not embed rcu\_head in object
- More RCU testing, experiment with modeling etc.
- More systematic study of \_\_rcu sparse checking.

- For questions, please email the list: [rcu@vger.kernel.org](mailto:rcu@vger.kernel.org)
  - Follow us on Twitter:
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Thank you!